

## austriamicrosystems AG

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# ams AG

The technical content of this austriamicrosystems application note is still valid.

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# AS5263

#### 12 bit Redundant Automotive Angle Position Sensor

## AS5263-DB Demoboard OPERATION MANUAL

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#### **1** General Description

The AS5263 is a redundant, contactless magnetic angle position sensor for accurate angular measurement over a full turn of 360°. A sub range can be programmed to achieve the best resolution for the application. It is a system-on-chip, combining integrated Hall elements, analog front end, digital signal processing and best in class automotive protection features in a single device.

To measure the angle, only a simple two-pole magnet, rotating over the center of the chip, is required. The magnet may be placed above or below the IC.

The absolute angle measurement provides instant indication of the magnet's angular position with a resolution of  $0.022^{\circ} = 16384$  positions per revolution. According to this resolution the adjustment of the application specific mechanical positions are possible.

The angular output data is available over a 12 bit PWM signal or 12 bit ratiometric analog output.

The AS5263 operates at a supply voltage of 5 V and the supply and output pins are protected against overvoltage up to +27 V. In addition the supply pins are protected against reverse polarity up to -18 V.

#### 2 The AS5263 Demoboard

The AS5263 demoboard is a complete rotary encoder system with built-in microcontroller and graphical LCD display. The board is externally supplied with a 9V battery or by the USB connection (standalone operation only).



Figure 1: AS5263 Demoboard hardware with mounted magnet knob

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#### 2.1 **Operating the AS5263 Demoboard**

#### The demoboard can be used only

#### As standalone unit supplied by a 9V battery or the USB connection

Connect the demoboard with one of above mentioned supplies. No other connections are required.

All AS5263 devices mounted on this demoboards, are un-programmed parts. Following settings can be chosen:

- 1. Full range operation pre-settings: 0-360deg / 0.5V-4.5V / analog
- 2. Full range operation pre-settings: 0-360deg / 0.5V-4.5V / PWM
- 3. Free programming: 0-360deg / 0.2V-4.8V (reduced voltage range, due to the upper and lower failure band) / analog or PWM

#### Mode selection

After connecting the board to the supply, follow these steps:

- 1. By turning the magnet knob counter-clockwise a marker appears
- 2. Select desired option and press button S1 to confirm
  - First and second option (pre-settings for analog and PWM) shows now the programming parameters to be set. Confirm these settings by pressing S1 again. The demoboard is programmed and provides now a) the read back analog values on the header P2 at pin Vout and on the display. The display shows

"analog mode active". b) the PWM signal on the header P2 at pin Vout only. The display shows "PWM mode active".

Third option (free programming) shows the start angle selection on the display. Chose the start angle with aid of the magnet knob and press S1 again (the angle is set in degree, the analog output voltage in Volts and the PWM output voltage in % of VDD). Please continue accordingly, until the display shows "analog mode active" or "PWM mode active".

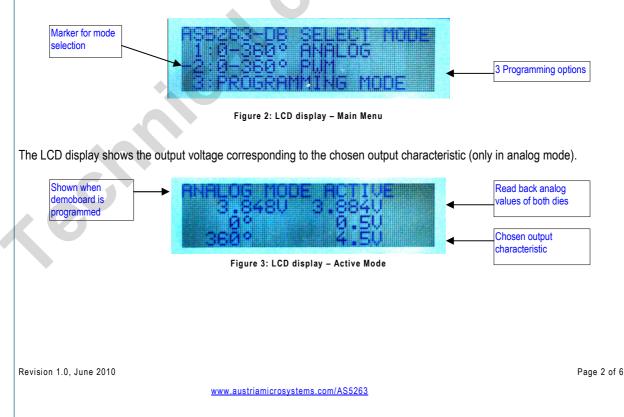
The clamping levels CLL and CLH are automatically set to the chosen start/end voltage levels.

Note: As long as the demobaord is not active (in free programming mode only), one can return to main menu by pressing button S1 for about 2 seconds.

Resetting the demoboard is done by disconntecing the supply!

#### 2.2 Graphic LCD display

The first display shows the main menu right after startup.



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If the magnet is too far away from the encoder, "Magnet Err" will be displayed.



Figure 4: LCD display – Missing Magnet

#### 2.3 Vout LED

The Vout LED is connected to the output of the AS5263. The output is analog and proportional to the angle of the magnet.

Viewing the output signal on the LED results in brightness, that is proportional to the angle of the magnet. When the angle of the magnet is at the start point, the LED is almost dark. Turning the knob towards higher angle values, increases the brightness of the LED.

### 2.4 Kick LED

He kick down is not activated in this version of demoboard, hence the Kick LED is always ON.

#### 2.5 Encoder selection switch

The switch S2 selects the encoder which communicates with the microcontroller.

- 1. Right position (default): Onboard AS5263
- Left Position: External AS5263 connected on P1 The signals of the interface (OUT) and the power supply (5V, GND) of an external device can be connected directly to P1. In this configuration, this data is displayed on the LCD.

An AS5263 can be attached to P1 and evaluated (see Figure 5). The picture shows only the connection for the bottom die. For using the top die, please connect the open pins of the external device accordingly.

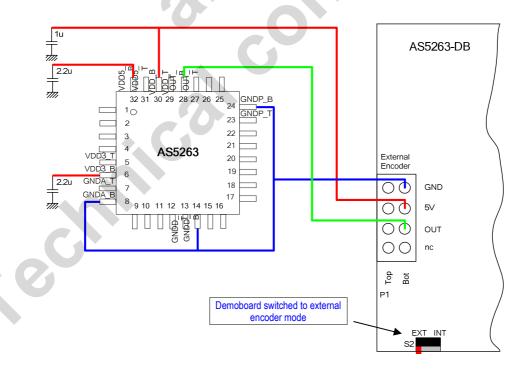
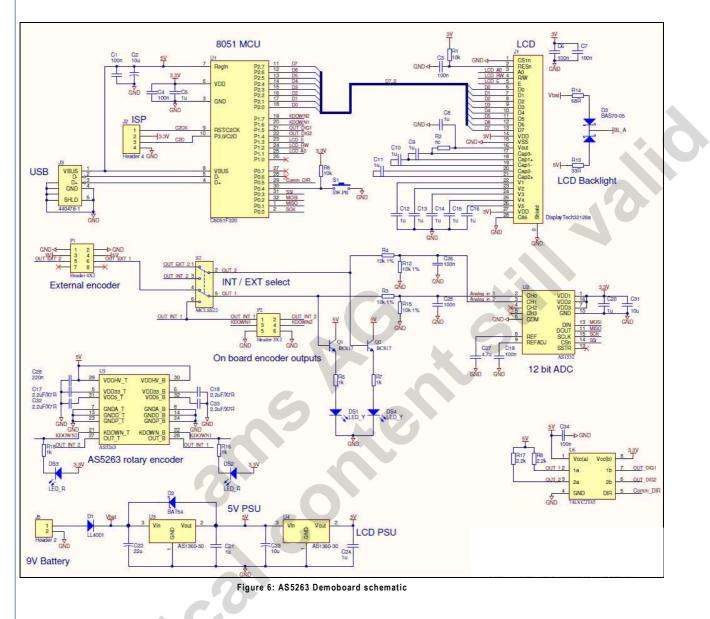


Figure 5: external AS5263 connection to the demoboard

Revision 1.0, June 2010

### 2.6 AS5263 Demoboard Schematic and Blockdiagram



AS5263 Programmable Magnetic Rotary Sensor

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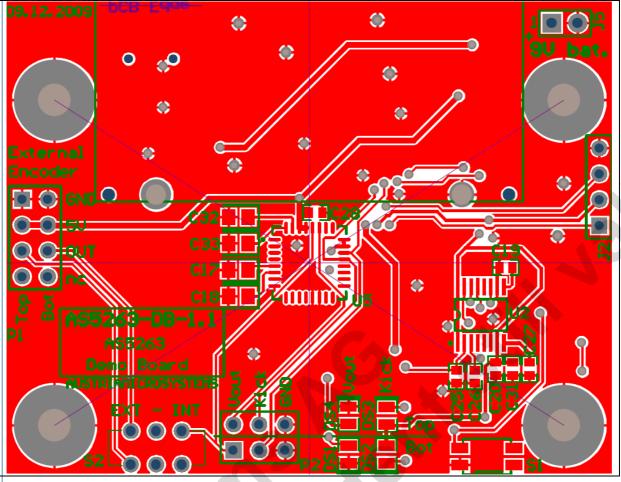


Figure 7: AS5263 Demoboard PCB Layout

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## **Revision History**

Revision	Date	Description
1.0	June 2010	First version

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